

Node-wise Localization of Graph Neural Networks

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Outline

- **Problem**
- Proposed model: LGNN
- Experiments
- Conclusions

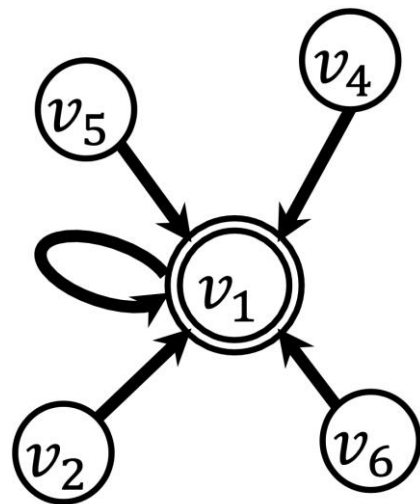
Problem: graph neural networks

- Graph neural networks (GNNs) [1, 2, 3]

$$\mathbf{h}_v^l = \sigma \left(\text{AGGR} \left(\{ \mathbf{W}^l \mathbf{h}_u^{l-1} : \forall u \in C_v \} \right) \right)$$

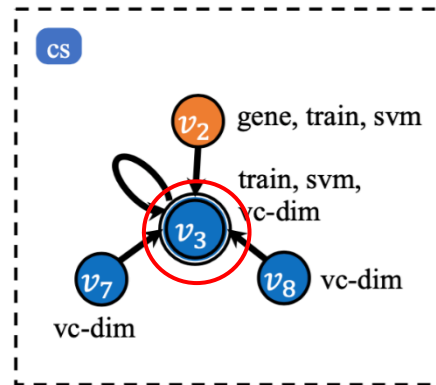
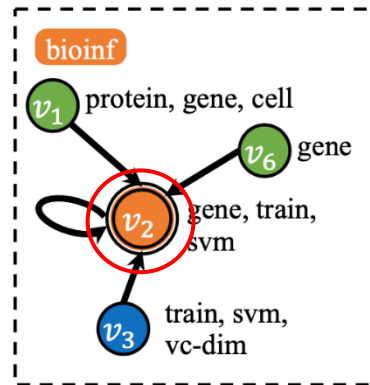
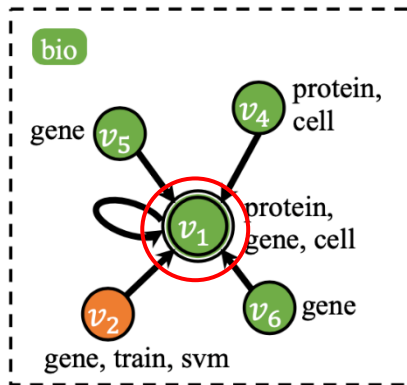
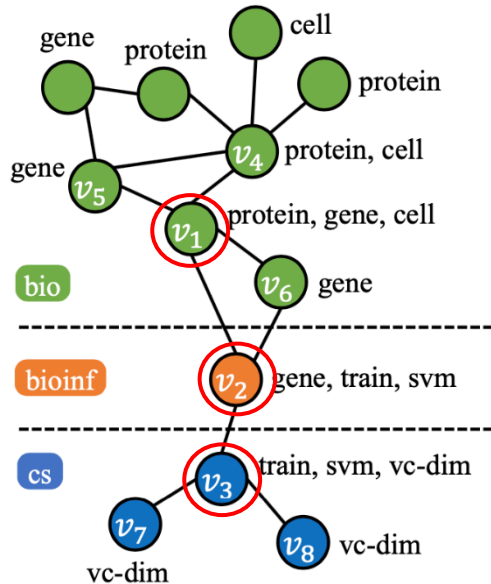
Aggregation function

- Node classification



- [1] Kipf, T. N., et al. 2017. Semi-supervised classification with graph convolutional networks. ICLR.
[2] Veličković, P., et al. 2018. Graph attention networks. ICLR.
[3] Xu K, et al. 2019. How powerful are graph neural networks? ICLR.

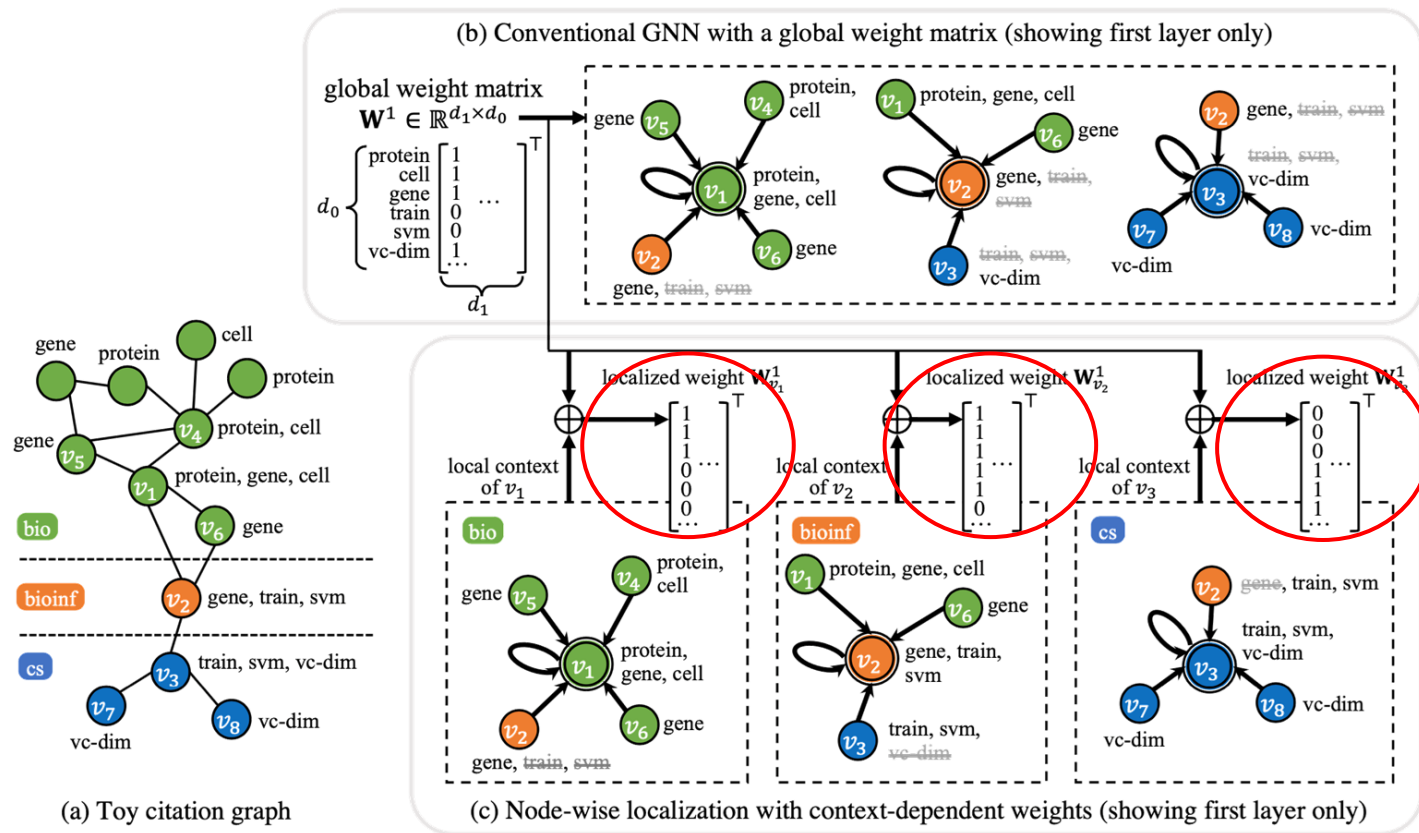
Problem: limitation of GNNs



- Different local context of each node
 - bio: v_1
 - bioinf: v_2
 - Cs: v_3

Can we allow each node to be parameterized by its own weight matrix?

Problem: Our Idea



- Localization
 - Localize the global model for each node
- Significance
 - Global vs. local
 - Node- and edge-level

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Proposed Model: Localization

- General formulation of Localization
 - Localized model

$$\Theta_v = f(\Theta, C_v)$$

Localized model
on v

Global model

Local context of v

- Local context of node v on graph $G = (V, E)$
$$C_v = \{v\} \cup \{u \in V : \langle v, u \rangle \in E\}$$

Proposed Model: Node-level Localization

- Global model: Conventional GNNs

$$\mathbf{h}_v^l = \sigma \left(\text{AGGR} \left(\left\{ \mathbf{W}^l \mathbf{h}_u^{l-1} : \forall u \in C_v \right\} \right) \right)$$

Aggregation function

Weight matrix

- Node-level localization

$$\mathbf{W}_v^l = \mathbf{W}^l \odot \left[(\mathbf{a}_v^l)_{\times d_l} \right]^\top + \left[(\mathbf{b}_v^l)_{\times d_l} \right]^\top$$

Localize the weight matrix

$$\mathbf{c}_v^l = \text{MEAN} \left(\left\{ \mathbf{h}_u^{l-1} : \forall u \in C_v \right\} \right)$$

Local context

$$\mathbf{a}_v^l = \sigma \left(\mathbf{M}_a^l \mathbf{c}_v^l \right) + \mathbf{1}, \quad \mathbf{b}_v^l = \sigma \left(\mathbf{M}_b^l \mathbf{c}_v^l \right)$$

Scaling and shifting factors

Proposed Model: Edge-level Localization

- Localization of GNNs
 - Edge-level localization

$$\mathbf{c}_{u,v}^l = \text{CONCAT}(\mathbf{h}_v^{l-1}, \mathbf{h}_u^{l-1}) \quad \text{Local context}$$

$$\mathbf{h}_v^l = \sigma(\text{AGGR}(\{\mathbf{W}_v^l \mathbf{h}_u^{l-1} \odot \mathbf{a}_{u,v}^l + \mathbf{b}_{u,v}^l : \forall u \in C_v\})) \quad \text{Aggregation}$$

$$\mathbf{a}_{u,v}^l = \sigma(\mathbf{N}_a^l \mathbf{c}_{u,v}^l) + \mathbf{1}, \quad \mathbf{b}_{u,v}^l = \sigma(\mathbf{N}_b^l \mathbf{c}_{u,v}^l) \quad \text{Scaling and shifting factors}$$

Proposed Model: Loss

- Semi-supervised node classification

$$\mathbf{z}_{v,k} = \text{SOFTMAX} \left(\mathbf{h}_{v,k}^\ell \right) = \frac{\exp(\mathbf{h}_{v,k}^\ell)}{\sum_{k'=1}^K \exp(\mathbf{h}_{v,k'}^\ell)}$$

– Overall loss

$$-\sum_{v \in V_Y} \sum_{k=1}^K Y_{v,k} \ln \mathbf{z}_{v,k} + \lambda_G \|\Theta_G\|_2^2 + \lambda_L \|\Theta_L\|_2^2$$

Parameters set of global GNN Parameters set of localization

$$+ \lambda \left(\|A - 1\|_2^2 / |A| + \|B\|_2^2 / |B| \right)$$

Contains all scaling factors Contains all shifting factors

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Datasets, evaluation and baselines

- Datasets

- Evaluation

- Accuracy, micro-F

Dataset	# Nodes	# Edges	# Classes	# Features
Cora	2,708	5,429	7	1,433
Citeseer	3,327	4,732	6	3,703
Amazon	13,381	245,778	10	767
Chameleon	2,277	36,101	5	2,325

- Baselines

- Embedding models: DeepWalk [1], Planetoid [2]
- GNN models: GCN [3], GAT [4], GIN [5]
- GNN-FiLM [6]: GCN-FiLM, GAT-FiLM, GIN-FiLM

[1] Perozzi B, et al. 2014. Deepwalk: Online learning of social representations. KDD.

[2] Yang Z, et al. 2016. Revisiting semi-supervised learning with graph embeddings. ICML.

[3] Kipf, T. N., et al. 2017. Semi-supervised classification with graph convolutional networks. ICLR.

[4] Veličković, P., et al. 2018. Graph attention networks. ICLR.

[5] Xu K, et al. 2019. How powerful are graph neural networks? ICLR.

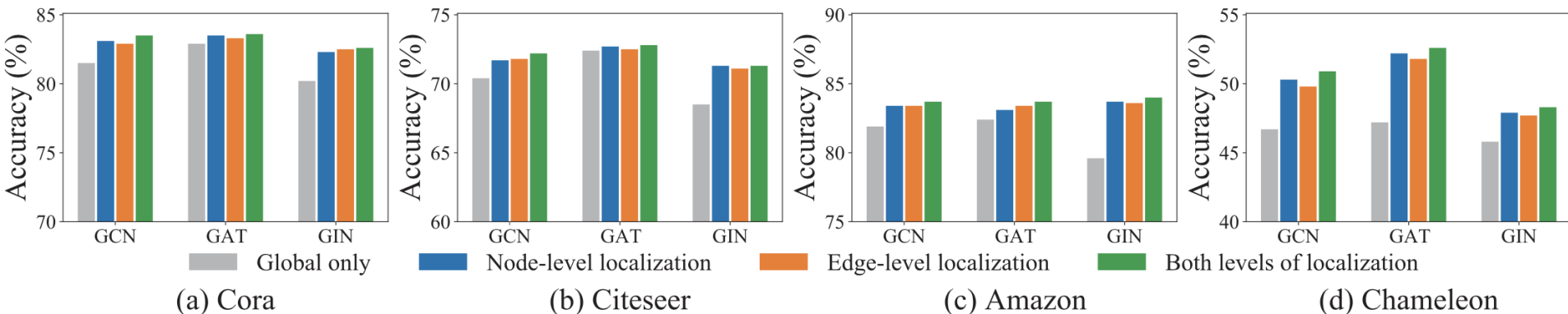
[6] Brockschmidt M. 2020. Gnn-film: Graph neural networks with feature-wise linear modulation. ICML.

Node classification

- LGNN consistently achieves significant performance boosts
- GAT-based models generally attain better performance than GCN- and GIN-based models
- Increasing the number of parameters alone cannot achieve the effect of localization

Methods	# Params (Cora)	Cora		Citeseer		Amazon		Chameleon	
		Accuracy	Micro-F	Accuracy	Micro-F	Accuracy	Micro-F	Accuracy	Micro-F
DeepWalk	693K	73.8±0.3	74.9±0.1	61.6±0.2	60.5±1.0	80.1±1.6	77.3±1.3	41.2±1.3	40.1±1.1
Planetoid	345K	66.1±0.4	64.5±0.5	64.5±0.3	62.9±0.4	69.8±1.7	64.5±1.5	39.3±1.8	37.7±1.7
GCN	11K	81.5±0.7	80.8±0.5	70.4±0.5	68.3±0.7	81.9±0.5	81.0±0.8	46.7±4.3	46.4±2.4
GCN-64	92K	82.0±0.3	80.9±0.3	71.1±0.3	69.2±0.4	82.1±0.5	81.2±0.8	48.3±3.3	46.3±1.8
GCN-96	138K	81.9±0.2	80.8±0.3	71.3±0.4	69.4±0.5	82.2±0.4	81.5±0.7	45.5±2.4	43.8±2.5
GCN-FiLM	35K	78.1±0.6	76.9±0.5	69.8±1.1	67.9±1.0	79.2±1.0	77.1±1.5	42.8±1.1	39.9±1.3
LGCN	104K	83.5±0.3	82.1±0.4	72.2±0.4	70.2±0.4	83.7±1.5	82.3±2.0	50.9±1.1	49.7±0.7
(improv.)	-	(1.8%)	(1.5%)	(1.3%)	(1.2%)	(1.8%)	(1.0%)	(5.4%)	(7.1%)
GAT	92K	82.9±0.6	82.0±0.6	72.4±0.7	70.4±0.8	82.4±1.3	80.1±1.9	47.2±1.1	46.2±2.1
GAT-64	738K	83.1±0.4	81.9±0.6	71.6±1.5	69.8±1.6	83.0±0.9	81.2±1.4	51.2±1.5	50.2±1.3
GAT-96	1108K	83.2±0.6	81.9±0.6	71.4±0.9	69.6±0.9	83.1±1.0	81.5±1.4	51.9±1.2	50.2±1.8
GAT-FiLM	277K	82.0±0.5	80.6±0.6	71.2±1.0	69.2±1.1	83.3±0.6	81.9±0.8	46.8±5.7	45.1±5.2
LGAT	836K	83.6±0.4	82.3±0.4	72.8±0.4	70.8±0.5	83.7±0.7	82.3±0.8	52.6±1.0	51.1±0.9
(improv.)	-	(0.5%)	(0.4%)	(0.6%)	(0.6%)	(0.5%)	(0.5%)	(1.3%)	(1.8%)
GIN	11K	80.2±0.5	78.8±0.3	68.5±0.7	66.5±1.0	79.6±1.7	78.5±2.6	45.8±3.0	41.2±4.0
GIN-64	92K	80.3±1.1	79.1±1.0	67.8±1.5	66.1±1.1	79.8±1.1	79.0±1.4	45.7±4.5	40.7±5.7
GIN-96	138K	79.9±1.1	78.9±1.0	68.6±1.4	66.6±1.6	80.2±2.1	79.0±3.2	45.9±3.5	41.5±4.1
GIN-FiLM	35K	79.8±0.7	78.5±0.5	67.7±1.4	65.8±1.5	78.6±2.8	77.2±3.3	38.8±2.6	34.2±2.9
LGIN	126K	82.6±0.8	81.6±0.8	71.3±0.4	69.5±0.5	84.0±1.2	82.7±1.7	48.3±1.9	47.3±1.9
(improv.)	-	(2.9%)	(3.2%)	(3.9%)	(4.4%)	(4.7%)	(4.7%)	(5.2%)	(14.0%)

Ablation study



- Utilizing only one module consistently outperforms the global model
- The node-level localization tends to perform better than edge-level localization.
- Modeling both jointly results in the best performance

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Conclusions

- Motivation
 - We identified the need to **localize GNNs** for different nodes
- Proposed model: **LGNN**
 - Encode graph-level general patterns using a **global weight matrix**
 - **Node-level** and **edge-level** localization
- Experiments
 - Extensive experiments demonstrate that LGNN significantly outperforms state-of-the-art GNNs.

Thanks!

Paper, code, data...

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